

# Generalizing Experimental Results by Leveraging Knowledge of Mechanisms

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## Abstract

We show how experimental results can be generalized across diverse populations by leveraging knowledge of local mechanisms that produce the outcome of interest, only some of which may differ in the target domain. We use Structural Causal Models (SCM) and a refined version of selection diagrams to represent such knowledge, and to decide whether it entails the invariance of *probabilities of causation* across populations, which then enables generalization. We further provide: (i) bounds for the target effect when some of these conditions are violated; (ii) new identification results for probabilities of causation and the transported causal effect when trials from multiple source domains are available; as well as (iii) a Bayesian approach for estimating the transported causal effect from finite samples. We illustrate these methods both with simulated data and with a real example that transports the effects of Vitamin A supplementation on childhood mortality across different regions.

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# 1 Introduction

Generalizing results of randomized control trials (RCT) is critical in many empirical sciences and demands an understanding of the conditions under which such generalizations are feasible. When the mechanisms that determine the outcome differ between the study population and the target population, generalization requires measuring the variables responsible for such differences or, if this is not possible, isolating them away by measuring other variables (Pearl and Bareinboim, 2014). Recent work (Huitfeldt et al., 2018, 2019; Huitfeldt, 2019) describes an interesting situation under which transportability across populations is feasible without such measurements. This feasibility, however, is not immediately inferable using a standard (non-parametric) selection diagram (Pearl and Bareinboim, 2014; Bareinboim and Pearl, 2016), because it relies on the invariance of only some components of the outcome mechanism, but not all.

In this paper, we use the theory of Structural Causal Models (SCM) (Pearl, 2009) to show how generalization in these settings can be modeled using ordinary structural equations, counterfactual logic and selection diagrams. We demonstrate that it requires two key assumptions: (i) the independence of causal factors that affect the outcome; and, (ii) *functional constraints* on how these factors interact to produce the outcome. The combination of these assumptions may entail the invariance of certain *probabilities of causation* (Pearl, 1999; Tian and Pearl, 2000) across domains, thus allowing the transport of causal effects in settings where non-parametric generalization is otherwise impossible.

We further extend the results of existing literature by: (i) relaxing the monotonicity assumption and providing bounds for the causal effect in the target domain; (ii) deriving novel identification and over-identification results for probabilities of causation, as well as the transported causal effect, when trials from multiple source domains are available; and, (iii) providing a Bayesian framework for estimating the transported causal effect from finite samples. We illustrate these methods both in simulated data and in a real example that generalizes the effects of Vitamin A supplementation on childhood mortality across different regions (Sommer et al., 1986; Muhilal et al., 1988; West Jr et al., 1991). Open source software for R implements the methods discussed in this paper.<sup>1</sup>

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<sup>1</sup>Available in <https://github.com/carloscinelli/generalizing>.

## 2 Motivating example

To fix ideas, we borrow the “Russian Roulette” example from Huitfeldt (2019). Although stylized, this intuitive example illustrates the key features of the problem.

### A Russian Roulette trial

Suppose the city of Los Angeles decides to run a randomized control trial (RCT) to assess the effect of playing “Russian Roulette” on mortality.<sup>2</sup> After running the experiment, the mayor of Los Angeles discovers that “Russian Roulette” is harmful: among those assigned to play Russian Roulette, 17.5% of the people died, as compared to only 1% among those who were not assigned to play the game (people can die due to other causes during the trial, for example, prior poor health conditions).

After hearing the news about the Los Angeles experiment, the mayor of New York City (a dictator) wonders what the overall mortality rate would be if the city forced everyone to play Russian Roulette. Currently, the practice of Russian Roulette is forbidden in New York, and its mortality rate is at 5% (4% higher than LA). The mayor thus asks the city’s statistician to decide *whether* and *how* one could use the data from from Los Angeles to predict the mortality rate in New York, once the new policy is implemented.

Intuitively, our causal knowledge of the domain permits us to answer the question posed by the NYC mayor. Mortality is a consequence of two “independent” processes (the game of Russian Roulette and prior health conditions of the individual), and while the first factor remains unaltered across cities, the second intensifies by a known amount (5% vs 1%). Moreover, we can safely assume that the two processes interact disjunctively, namely, that death occurs if and only if at least one of the two processes takes effect. From these two assumptions and elementary probability theory, we can conclude that mortality in NYC would be 20.8%. In section 3 we will cast this intuition into a formal setting, define this notion of “independence,” and show how the data from NYC and LA should be combined to match our expectation. But before that, let us examine how this intuition clashes with the conclusion of a coarse analysis using selection diagrams.

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<sup>2</sup>Russian Roulette consists of loading a bullet into a revolver, spinning the cylinder, pointing the gun at one’s own head and then pulling the trigger. We do not recommend attempting this.

## An “impossibility” result

Selection diagrams are causal diagrams enriched with “selection nodes”  $S$ , usually represented by square nodes (■). These new nodes are used by the analyst to indicate which *local mechanisms* are suspected to differ between two environments (in our example, the mortality mechanism is suspected to differ between Los Angeles and New York). More importantly, the absence of a selection node pointing to a variable represents the *assumption* that the local mechanism responsible for assigning the value to that variable is the same in the two populations (Pearl, 1995, 2009; Pearl and Bareinboim, 2014; Bareinboim and Pearl, 2016).

To build our selection diagram, we need to introduce some notation. The population of Los Angeles will be denoted by  $\Pi$  (the “source population”) and that of New York by  $\Pi^*$  (the “target population”). The random variable  $Y$  stands for mortality, with events  $Y = 1$  denoting “death” and  $Y = 0$  denoting “survival;” the random variable  $X$  stands for the “treatment” assignment, with events  $X = 1$  denoting “play Russian Roulette” and  $X = 0$  denoting “not play Russian Roulette.” The random variable  $Y_x$  denotes the potential response of  $Y$  when the treatment  $X$  is experimentally set to  $x$ . Thus, mathematically, the findings of the RCT can be translated to  $P(Y_1 = 1) = 17.5\%$  and  $P(Y_0 = 1) = 1\%$ , and the available data from New York is  $P^*(Y_0 = 1) = 5\%$ . Our task is to estimate  $P^*(Y_1 = 1)$ .

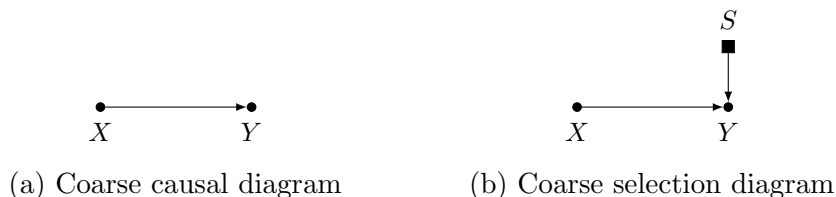


Figure 1: Coarse causal (a) and selection (b) diagrams of the Russian Roulette trial. The presence of  $S \rightarrow Y$  in (b) correctly prohibits the naive transportation of the interventional distribution  $P(Y_x)$  from the source  $\Pi$  (Los Angeles) to the target environment  $\Pi^*$  (New York).

The coarsest causal diagram of the Russian Roulette trial comprises only the treatment  $X$  and the outcome  $Y$ , as shown in Figure 1a. To move from the causal diagram to the selection diagram, we need to think of what may differ between LA and NYC. Since we already know from the data that

$P(Y_0 = 1) \neq P^*(Y_0 = 1)$ , we suspect there are differences in the way mortality is determined in the two cities (for example, people in New York may be in poorer health conditions, or the air quality may be worse). Thus, the selection diagram must contain a selection node  $S$  pointing to the mortality variable  $Y$  to indicate this disparity, as shown in Figure 1b.

Graphically, checking whether a causal relationship is transportable from one environment to another involves checking whether there exists a set of measurements that  $d$ -separates (Pearl, 2009) the source of disparity (the selection node  $S$ ) from our target quantity. The presence of the selection node pointing directly into  $Y$  prevents the separation of  $S$  from  $Y$ , and leads us to conclude that transportability is impossible without further assumptions. On the other hand, the intuition that led us to predict the new mortality rate in NYC tells us that such assumptions, once formalized, could license transportability. This intuition, as we discussed, was based on two assumptions that are not shown in the coarse selection diagram of Figure 1. The diagram represents only the existence of a disparity between LA and NYC, not the fact that it is localized to one cause of death (prior health factors), and that it does not extend to the other cause (the game of Russian Roulette). As a result, the diagram correctly warns us that, absent further assumptions, we are not authorized to make any generalization between the two cities.

### 3 Building the structural model

We now explicate formally what we know about the game of “Russian Roulette” and health factors, and show how this knowledge renders transportability possible.

#### Prior health conditions *versus* physical mechanism

To represent the two causes of death, we refine our model by defining two extra random variables,  $B$  and  $H$ : (i)  $B$  denotes “bad luck” when playing Russian Roulette, and its values represent a match ( $B = 1$ ) or mismatch ( $B = 0$ ) between the trigger and the location of the bullet in the cylinder; (ii) and  $H$  denotes *all* other health factors producing death ( $H = 1$ ) or survival ( $H = 0$ ). Accordingly, our causal diagram will contain two new edges,  $H \rightarrow Y$  and  $B \rightarrow Y$ , since both “health conditions” and “bad luck” are key determinants of mortality  $Y$ . The updated causal diagram is shown

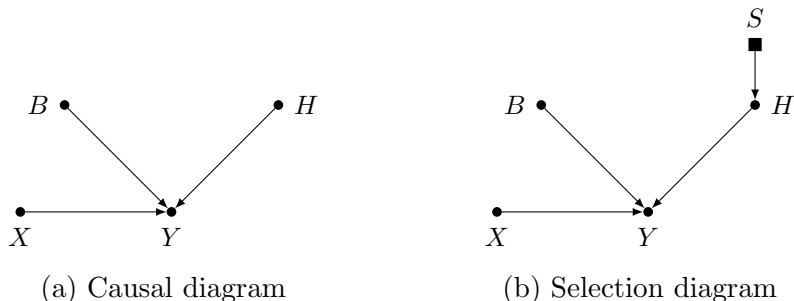


Figure 2: New causal (a) and selection (b) diagrams explicitly including the variables “health conditions” ( $H$ ) and “bad luck” ( $B$ ) when playing Russian Roulette. Here the analyst asserts (using the selection node  $S$ ) that  $H$  may differ between LA and NYC, but assumes that the mechanism triggering  $B$  is the same between the two cities. Also important is the absence of a directed edge or a bidirected edge between  $H$  and  $B$ .

Figure 2a. Note the absence of a directed or bidirected edge between  $H$  and  $B$ , which encodes our assumption that these two mechanisms are activated independently of each other.<sup>3</sup>

The new model helps us see more clearly the commonalities and disparities between LA and NYC. First, since there is a multitude of factors that can affect prior health conditions, and those are likely to differ between the two cities (as suggested by the observed difference  $P(Y_0 = 1) \neq P^*(Y_0 = 1)$ ), we again introduce a selection node pointing to  $H$ . Moreover, to encode the assumption that the probability of “bad luck” occurring is the same in both cities, we do not connect  $B$  to a selection node.<sup>4</sup> The new selection diagram is shown in Figure 2b.

The diagram of Figure 2b now guides us toward leveraging the data obtained in LA to make predictions in NYC. If we can find a way to *block the source of disparity originating from  $H$* , we would be left with the invariant physical mechanism shared by both cities. However, since  $H$  is unobserved, blockage is impossible without further assumptions. We now ask whether

<sup>3</sup>The arrow  $X \rightarrow Y$  comprises, of course, many intermediate mechanisms (such as loading the gun, spinning the cylinder, pulling the trigger) that are not modeled explicitly.

<sup>4</sup>Note that, although reasonable, one cannot take this assumption for granted—it could be the case that revolvers used for Russian Roulette in New York have a different number of chambers than those used in Los Angeles. *The absence of a selection node pointing to  $B$*  encodes the *assumption* that this is not the case.

our understanding of how the two mechanisms interact in producing  $Y$  would permit us to estimate  $P^*(Y_1 = 1)$ .

## Leveraging functional constraints

Our understanding that mortality is caused by *either one* of the two processes (prior health conditions or bad luck in the game), dictates the following *functional specification* for the *structural equation* of  $Y$ ,

$$Y = H \vee (X \wedge B) \tag{1}$$

Where  $\vee$  denotes the logical “or” operator, and  $\wedge$  denotes the logical “and” operator. Like any structural equation, Equation 1 defines the potential outcomes  $Y_0$  and  $Y_1$  (Pearl, 2009, Ch.7) which we may now find useful to encode explicitly. Its first implication is that  $Y_0 = H$  and  $Y_1 = H \vee B = Y_0 \vee B$ . This tells us that, once we know the potential response of units under no treatment ( $Y_0$ ) we do not need to know anything else about their previous health condition ( $H$ ) to determine the value of  $Y_1$ — $B$  would suffice.<sup>5</sup> We can represent this fact in a modified selection diagram, in which the potential outcomes are now also shown explicitly (Figure 3). The diagram reveals that  $Y_0$  blocks the source of health disparities between the two populations, and we conclude that  $Y_1 \perp\!\!\!\perp S \mid Y_0$ .<sup>6</sup>

More concretely, consider the counterfactual quantity

$$\text{PS}_{01} := P(Y_1 = 1 \mid Y_0 = 0)$$

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<sup>5</sup>Although here we have  $Y_0 = H$  for simplicity, this need not be the case. The same argument would hold, for instance, if we define  $H$  to be a random variable with arbitrary cardinality and  $Y = g(H) \vee (X \wedge B)$ , where  $g(H) \in \{0, 1\}$ . Likewise, see Appendix A.1 for an example where the treatment variable  $X$  is continuous and the same strategy adopted here can be employed.

<sup>6</sup>Since some relationships in the graph may be deterministic, conditional independencies other than those revealed by  $d$ -separation (with lower-case d) may be present. A complete criterion for DAGs with deterministic nodes is given by the  $D$ -separation criterion (with capital D) of Geiger et al. (1990). Moreover, note arrows between potential outcomes need not convey causal influence; their purpose is merely to ensure that the correct conditional independencies among variables are encoded in the graph, *as derived from the structural equations*. Finally, here we are not treating the question of how scientists acquire scientific knowledge in the form of a functional specification such as Equation 1. Rather, our task is more modest: given that scientists sometimes have knowledge of mechanisms, how can we leverage some of that knowledge for identification.

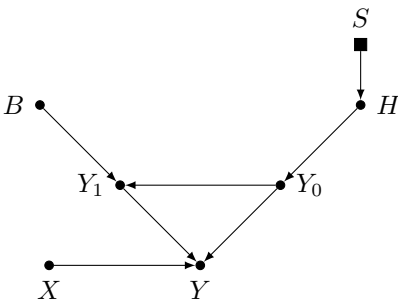


Figure 3: Selection diagram explicitly showing the potential outcomes  $Y_0$  and  $Y_1$  as implied by the functional constraints. Note that  $Y_1 \perp\!\!\!\perp S \mid Y_0$ .

which stands for the share of people who would die if forced to play Russian Roulette, among those who would not have died if not forced to do so. In other words,  $PS_{01}$  represents the probability that the game of Russian Roulette is *sufficient to kill* a person *during the trial*. The acronym  $PS_{01}$  was chosen to emphasize its relation to the “probability of sufficiency” (PS),  $PS = P(Y_1 = 1 \mid Y = 0, X = 0)$ , as defined and analyzed in Pearl (1999) and Tian and Pearl (2000). In our context, since the treatment is randomized, the two quantities coincide,

$$P(Y_1 = 1 \mid Y_0 = 0) = P(Y_1 = 1 \mid Y_0 = 0, X = 0) = P(Y_1 = 1 \mid Y = 0, X = 0)$$

where the first equality is licensed by the randomization of  $X$  and the second equality is due to consistency. In general, however,  $PS_{01}$  need not be the same as PS—the later measures the probability of fatal treatment among those who, given the choice, would *choose* not to be treated and survive; the former measures the probability of fatal treatment among those who would survive had they not been *assigned* for treatment.<sup>7</sup> Similar reasoning holds for  $PS_{10} := P(Y_1 = 0 \mid Y_0 = 1)$ , which stands for the probability that playing Russian Roulette is *sufficient to save* a person who would die if denied treatment. In our example, this probability is obviously zero as we shall formally show below. The condition  $Y_1 \perp\!\!\!\perp S \mid Y_0$ , implied by the diagram, states that these *probabilities of causation* are invariant across cities.<sup>8</sup> This

<sup>7</sup>For example, in legal settings, where acts are executed by *choice*, conditioning on the *observed*  $X$  gives a more appropriate measure of an agent’s responsibility, as argued in Pearl (2009, Ch. 9) and Pearl (2015).

<sup>8</sup>Probabilities of causation have been extensively studied elsewhere under a different context. See Pearl (1999); Tian and Pearl (2000); Pearl (2009).



feature of invariance, which is important in its own right, follows solely from our structural assumption about the mechanisms involved.

A second implication of Equation 1 is that the treatment effect is *monotonic*, that is  $Y_1 \geq Y_0$  for all individuals. This, in turn, implies  $PS_{10} = 0$ ; in other words, an individual that would have died of other causes during the trial, would still die if forced to play Russian Roulette. It has been shown that monotonicity is sufficient for identifying  $PS_{01}$  in this setting (Pearl, 1999; Tian and Pearl, 2000; Huitfeldt et al., 2018). Indeed, by the law of total probability,

$$P(Y_1 = 1) = (1 - PS_{10})P(Y_0 = 1) + PS_{01}(1 - P(Y_0 = 1))$$

The quantity  $P(Y_0 = 1)$  is given from the RCT (1%) and, due to monotonicity,  $PS_{10} = 0$ . Thus, we have:

$$PS_{01} = \frac{P(Y_1 = 1) - P(Y_0 = 1)}{1 - P(Y_0 = 1)} = \frac{17.5\% - 1\%}{99\%} = 1/6$$

This is not surprising; the probability that the “treatment” is *sufficient* to kill an individual who would have otherwise survived indeed equals  $1/6$ —the probability of having “bad luck” in the game of Russian Roulette, using a revolver with six chambers.<sup>9</sup>

Thus far we have established that  $PS_{10} = PS_{10}^*$ ,  $PS_{01} = PS_{01}^*$ , and that  $PS_{10} = 0$ ,  $PS_{01} = 1/6$ . Combining these results with the current baseline mortality from NYC, that is,  $P^*(Y_0 = 1) = 5\%$ , we can finally evaluate our target quantity  $P^*(Y_1 = 1)$ ,

$$\begin{aligned} P^*(Y_1 = 1) &= (1 - PS_{10}^*)P^*(Y_0 = 1) + PS_{01}^*(1 - P^*(Y_0 = 1)) \\ &= (1 - PS_{10})(5\%) + PS_{01}(95\%) \\ &= (1)(5\%) + (1/6)(95\%) = 20.8\% \end{aligned}$$

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<sup>9</sup>The right-hand side of this expression is known as the “relative difference,” or “susceptibility.” Simple algebra shows that  $\frac{P(Y_1=1)-P(Y_0=1)}{1-P(Y_0=1)} = 1 - \frac{1-P(Y_1=1)}{1-P(Y_0=1)}$ , where the quantity  $\frac{1-P(Y_1=1)}{1-P(Y_0=1)}$  is known as the “survival ratio.” Since under the assumption of monotonicity these estimands identify  $PS_{01}$ , and  $PS_{01}$  is invariant across domains, it thus follows that the “relative difference” and the “survival ratio” will also be equal between populations. Huitfeldt et al. (2018) suggested using this fact as a rationale for assuming homogeneity of effect measures across domains, a common heuristic among epidemiologists for approaching generalizability problems. These equivalences, however, break down without monotonicity; in that case, the “relative difference” is a lower bound for the probability of sufficiency (Tian and Pearl, 2000), as we discuss next.

Which matches the intuitive answer obtained in Section 2.

As a brief remark, note that, if instead of  $Y_1 \perp\!\!\!\perp S \mid Y_0$  we had obtained the condition  $Y_0 \perp\!\!\!\perp S \mid Y_1$ , we would conclude that the probabilities  $\text{PN}_{01} := P(Y_0 = 0 \mid Y_1 = 1)$  and  $\text{PN}_{10} := P(Y_0 = 0 \mid Y_1 = 0)$  are the same across trials. These quantities represent the probability that the treatment is *necessary* for causing ( $\text{PN}_{01}$ ) or preventing ( $\text{PN}_{10}$ ) the outcome during the experiment. All results of this paper hold in this setting, with minor modifications. Therefore, for simplicity of exposition, in the remainder of the text we discuss the case of  $Y_1 \perp\!\!\!\perp S \mid Y_0$  only.<sup>10</sup>

## Bounds without monotonicity

A key step in obtaining a point estimate for  $P^*(Y_1 = 1)$  was the monotonicity property, which emanates from the functional form of Equation 1. Monotonicity allowed us to identify the probabilities of sufficiency  $\text{PS}_{01}$  and  $\text{PS}_{10}$ , which, as advertised by the assumptions in the selection diagram of Figure 3, are invariant across domains. The monotonicity property holds trivially in our example of the Russian Roulette, when  $Y$  represents death, but it may not hold for other outcomes or, more generally, it may not hold in contexts beyond our stylized example.

Remarkably, however, even in the absence of monotonicity, one can still assess the transported causal effect, albeit in the form of a *bound*. The next theorem shows that the counterfactual independence  $Y_1 \perp\!\!\!\perp S \mid Y_0$  by itself is strong enough for bounding the causal effect in the target domain. These results improve the bias analysis performed by Huitfeldt et al. (2018), and provide an exact characterization of the inferences compatible with the assumption of  $Y_1 \perp\!\!\!\perp S \mid Y_0$ .

**THEOREM 1.** *Consider a source domain  $\Pi$  and a target domain  $\Pi^*$ . Let  $P_{ij} := P(Y_i = j)$ ,  $P_{ij}^* := P^*(Y_i = j)$ , and let  $RR = \frac{P_{11}}{P_{01}}$  denote the risk-ratio in the trial of the source domain  $\Pi$ . If  $Y_1 \perp\!\!\!\perp S \mid Y_0$ , then  $P_{11}^*$  of  $\Pi^*$  is bounded by*

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<sup>10</sup>For example, under the assumption of monotonicity, we have that  $\text{PN}_{01} = \frac{P(Y_1=1) - P(Y_0=1)}{P(Y_1=1)}$  (Pearl, 1999). This last estimand is known as the “excess-risk-ratio,” and algebra also shows that  $\frac{P(Y_1=1) - P(Y_0=1)}{P(Y_1=1)} = 1 - \frac{1}{P(Y_1=1)/P(Y_0=1)}$ , where  $\frac{P(Y_1=1)}{P(Y_0=1)}$  is the “risk ratio.” Thus in this setting, both the “excess-risk-ratio” and the “risk ratio” would be equal across domains. Without monotonicity, the “excess-risk-ratio” is a lower bound on the probability of necessity (Tian and Pearl, 2000).

$P_{11}^{*L} \leq P_{11}^* \leq P_{11}^{*U}$ , with,

$$P_{11}^{*L} = RR \times P_{01}^* + \min \left\{ \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) PS_{01}^L, \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) PS_{01}^U \right\},$$

$$P_{11}^{*U} = RR \times P_{01}^* + \max \left\{ \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) PS_{01}^L, \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) PS_{01}^U \right\}$$

where  $PS_{01}^L = \max \left\{ 0, \frac{P_{11} - P_{01}}{1 - P_{01}} \right\}$  and  $PS_{01}^U = \min \left\{ \frac{P_{11}}{1 - P_{01}}, 1 \right\}$  are the lower and upper bounds on  $PS_{01}$ , respectively.

*Proof.* The bounds are obtained by solving a linear optimization problem, as detailed in Appendix A.2.  $\square$

Theorem 1 can be better understood as a two-stage process. First, with a little algebra, it is possible to re-express  $P^*(Y_1 = 1)$  as a function of  $PS_{01}$  alone, resulting in,

$$P^*(Y_1 = 1) = RR \times P^*(Y_0 = 1) + \left( \frac{P(Y_0 = 1) - P^*(Y_0 = 1)}{P(Y_0 = 1)} \right) PS_{01} \quad (2)$$

Where  $RR = P(Y_1 = 1)/P(Y_0 = 1)$  denotes the *risk-ratio* obtained in the trial of the source domain  $\Pi$ . The first term of this expression,  $RR \times P^*(Y_0 = 1)$ , consists of the “naive” prediction for  $P^*(Y_1 = 1)$  that one would have obtained by assuming a constant risk ratio across populations. The second term adjusts this naive prediction, by taking into account both the excess risk-ratio of contrasting the baseline mortality between  $\Pi$  and  $\Pi^*$ , as well as the probability of sufficiency shared across environments,  $PS_{01}$ .

After this, note that, although the probability of sufficiency  $PS_{01}$  in Equation 2 cannot be point identified, it can be bounded by (see Appendix A.2 as well as Tian and Pearl (2000))

$$\max \left\{ 0, \frac{P(Y_1 = 1) - P(Y_0 = 1)}{1 - P(Y_0 = 1)} \right\} \leq PS_{01} \leq \min \left\{ \frac{P(Y_1 = 1)}{1 - P(Y_0 = 1)}, 1 \right\} \quad (3)$$

Thus, by substituting  $PS_{01}$  with its bounds, we obtain the desired bounds for the target quantity  $P^*(Y_1 = 1)$ .

For instance, in our Russian Roulette example, regardless of whether monotonicity holds,  $PS_{01}$  can be bounded by

$$16.7\% \leq PS_{01} \leq 17.7\%$$

And this assures us that  $P^*(Y_1 = 1)$  must lie between,

$$16.8\% \leq P^*(Y_1 = 1) \leq 20.8\%$$

To put it another way, the results of the trial in LA tells us that implementing the policy in NYC would cause *at least* an increase of  $16.8\% - 5\% = 11.8\%$  and *at most* an increase of  $20.8\% - 5\% = 15.8\%$  in mortality. Note that, here, substituting the lower bound for  $PS_{01}$  (16.7%) actually translates to the *upper bound* for  $P^*(Y_1 = 1)$  (20.8%). This happens because the baseline risk in the target population  $\Pi^*$  is *higher* than that of the source population  $\Pi$ , and thus the adjustment due to  $PS_{01}$ , in Equation 2, is negative.

These considerations naturally lead to the question: in general, how informative are the bounds on  $P^*(Y_1 = 1)$ ? It turns out that the width of the bounds have a simple characterization. Consider the case in which the bounds for  $PS_{01}$  are not zero nor one. Now let  $P^{*U}(Y_1 = 1)$  and  $P^{*L}(Y_1 = 1)$  denote the upper and lower bound on  $P^*(Y_1 = 1)$ , respectively. After some algebra, it is possible to show that (see Appendix A.2),

$$P^{*U}(Y_1 = 1) - P^{*L}(Y_1 = 1) = \frac{|P(Y_0 = 1) - P^*(Y_0 = 1)|}{1 - P(Y_0 = 1)} \quad (4)$$

That is, in this setting, the width of the bounds depends on the baseline risks  $P(Y_0 = 1)$  and  $P^*(Y_0 = 1)$  alone. Moreover, even if the bounds for  $PS_{01}$  happen to be “wide,” if the baseline risks are close enough across populations, the bounds for  $P^*(Y_1 = 1)$  can still be “narrow.” In Section 4 we illustrate this fact with a real data example in which the bounds are narrow enough to imply a positive effect of the treatment.

## Identification with trials from multiple source domains

In Theorem 1 we learned that the existence of experimental data from *one* source population leads to bounds on the transported causal effect of the target population, although it is not enough for its point identification. Surprisingly, however, if we can obtain experimental data from an additional source population, this suffices to change the picture. With *two* source trials, it is possible to obtain a point estimate for the probabilities of sufficiency, and, consequently, for  $P^*(Y_1 = 1)$  without invoking monotonicity, nor any further assumptions beyond  $Y_1 \perp\!\!\!\perp S \mid Y_0$ . Moreover, multiple source trials en-

tail strong testable implications that can be used to *falsify* this “cross-world” assumption.<sup>11</sup>

To illustrate, consider our Russian Roulette example, and suppose we learn that the city of Chicago has also performed an RCT. In that trial, 25% of those assigned to play the game died, in contrast to 10% of those not assigned to play. If the selection diagram contrasting NYC with Chicago is the same as that of Figure 3, we can combine the results from LA and Chicago to estimate the probabilities of sufficiency shared across cities. By the law of total probability, expand the expression for  $P(Y_1 = 1)$ , both for LA and Chicago, to obtain a system of two equations and two unknowns:

$$\text{(LA Equation):} \quad 0.175 = (1 - \text{PS}_{10}) \times 0.01 + \text{PS}_{01} \times 0.99 \quad (5)$$

$$\text{(Chicago Equation):} \quad 0.250 = (1 - \text{PS}_{10}) \times 0.10 + \text{PS}_{01} \times 0.90 \quad (6)$$

This system can then be solved for  $\text{PS}_{10}$  and  $\text{PS}_{01}$

$$\text{PS}_{10} = 0, \quad \text{PS}_{01} = 1/6$$

Put differently, the *only* values for  $\text{PS}_{10}$  and  $\text{PS}_{01}$  that are compatible with the observed data from *both* trials (LA and Chicago) are that: (i) the “treatment” cannot save anyone from dying; and, that (ii) the treatment kills 1/6 of those who would not have died otherwise. These are the same numeric values as before, but with an important difference—we did not assume monotonicity to obtain point identification; instead, we learned *from the data* that the treatment effect must be monotonic. Once we have these numbers, we can use the same strategy as before to predict the causal effect in NYC, which amounts to, again, 20.8%.

Furthermore, since  $\text{PS}_{10}$  and  $\text{PS}_{01}$  must be valid probabilities, not all observed values are compatible with the assumption that  $Y_1 \perp\!\!\!\perp S \mid Y_0$ . For instance, suppose that instead of 10%, the observed baseline mortality rate in Chicago were 5%. This would imply the impossible value  $\text{PS}_{10} = -1.03$ , thus *falsifying* the assumption of invariance across domains. It is also easy to see that with three or more source domains we obtain over-identification, since each population pair implies different estimates for  $\text{PS}_{10}$  and  $\text{PS}_{01}$ . If those estimates are discordant, this calls into question the assumption

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<sup>11</sup>Similar observations regarding testable implications when combining information from multiple studies have also been made in Hartman et al. (2015), Lu et al. (2019) and Dahabreh et al. (2020).

of  $Y_1 \perp\!\!\!\perp S \mid Y_0$ . These results are somewhat reassuring. They tell us that, despite its “cross-world” nature, the assumption of invariance of probabilities of causation across domains may have strong testable implications, and can thus be subjected to empirical scrutiny.

We formalize the previous considerations with the next two theorems.

**THEOREM 2.** *Consider two source domains  $\Pi^a$  and  $\Pi^b$ . Let the probabilities of sufficiency be the same across the two populations, that is,  $PS_{01}^a = PS_{01}^b = PS_{01}$  and  $PS_{10}^a = PS_{10}^b = PS_{10}$ . Then,*

$$PS_{10} = 1 - \frac{P_{11}^a P_{00}^b - P_{11}^b P_{00}^a}{P_{01}^a P_{00}^b - P_{01}^b P_{00}^a}$$

$$PS_{01} = \frac{P_{11}^b P_{01}^a - P_{11}^a P_{01}^b}{P_{01}^a P_{00}^b - P_{01}^b P_{00}^a}$$

Where  $P_{ij}^a := P^a(Y_i = j)$  and  $P_{ij}^b := P^b(Y_i = j)$ . Moreover, the experimental probabilities of necessity, and probability of necessity and sufficiency (Tian and Pearl, 2000) of both populations are also identifiable from experimental data of  $\Pi^a$  and  $\Pi^b$ .

*Proof.* As explained in the text, we can use the law of total probability for each domain to obtain two linear equations with two unknowns,  $PS_{01}$  and  $PS_{10}$ . We can thus (generically) solve the system of equations for those quantities. Interestingly, in this setting, not only the probabilities of sufficiency, but *all* remaining probabilities of causation (as discussed in Tian and Pearl (2000)), are also identifiable. See details in Appendix A.2.  $\square$

Next, the causal effect for a target population  $\Pi^*$  can be transported by appealing again to the law of total probability.

**THEOREM 3.** *Consider two source domains  $\Pi^a$ ,  $\Pi^b$ , and a target domain  $\Pi^*$ . Let the probabilities of sufficiency be the same across populations, that is,  $PS_{01}^a = PS_{01}^b = PS_{01}^*$  and  $PS_{10}^a = PS_{10}^b = PS_{10}^*$ . Then, the causal effect  $P_{11}^*$  in  $\Pi^*$  is given by,*

$$P_{11}^* = \frac{P_{11}^a P_{00}^b - P_{11}^b P_{00}^a}{P_{01}^a P_{00}^b - P_{01}^b P_{00}^a} \times P_{01}^* + \frac{P_{11}^b P_{01}^a - P_{11}^a P_{01}^b}{P_{01}^a P_{00}^b - P_{01}^b P_{00}^a} \times P_{00}^*$$

## 4 A Bayesian approach to estimation

The previous results focused on *identification*, that is, they are “asymptotic,” and assume that the measured quantities are representative of their corresponding quantities in the population. In practice, however, researchers need to take sampling uncertainty into account. In this section, we describe a Bayesian framework that practitioners can easily put to use for finite sample inference. A Bayesian approach is especially suited for this setting—when the target quantity  $P^*(Y_1 = 1)$  is not identifiable from the data alone, preference for any value of the parameter within the identified bounds must rely on prior knowledge.

### Model specification

The Bayesian specification of our model can be simplified if we use *counts*. For the source population  $\Pi$ , let  $n_0$  denote the *sum* of individuals with  $Y = 1$  in the control group, and let  $n_1$  denote the *sum* of individuals with  $Y = 1$  in the treatment group. Likewise, let  $n_0^*$  and  $n_1^*$  denote those quantities for the target population  $\Pi^*$ . Note that  $n_1^*$  is not observed, since the target population is under the “no-treatment” regime.

Now let us use the same notation of Theorem 1 to denote population parameters, that is:  $P_{11} := P(Y_1 = 1)$ ,  $P_{01} := P(Y_0 = 1)$ ,  $P_{01}^* := P^*(Y_0 = 1)$ ,  $P_{11}^* := P^*(Y_1 = 1)$ . Given that the outcome variable  $Y$  is binary, the sum of individuals with  $Y = 1$  follows a binomial distribution, and we can write the model for the observed data  $\mathcal{D} = \{n_0, n_1, n_0^*\}$  as,

$$n_0 \sim \text{Binomial}(N_0, P_{01}) \tag{7}$$

$$n_1 \sim \text{Binomial}(N_1, P_{11}) \tag{8}$$

$$n_0^* \sim \text{Binomial}(N_0^*, P_{01}^*) \tag{9}$$

where  $N_0$  denotes the total number of individuals in the control arm, and  $N_1$  the total number of individuals in the treatment arm of the trial in the source population;  $N_0^*$  denotes the total sample size of the target population (which is under the no-treatment regime). We treat  $N_0$ ,  $N_1$  and  $N_0^*$  as *known* fixed quantities. Note the observed data depends *only* on the parameters  $P_{01}$ ,  $P_{11}$  and  $P_{01}^*$ .

We now need to specify the prior distribution of the parameters and the target quantities of interest. Here we describe two general alternatives, depending on whether the researcher is interested in making inferences directly

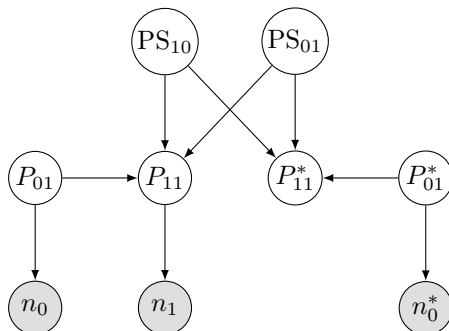


Figure 4: Probabilistic graphical model for Bayesian inference when the quantity of interest is  $P_{11}^*$ . Gray nodes ( $n_0$ ,  $n_1$ ,  $n_0^*$ ) denote observed variables. White nodes denote latent parameters ( $P_{01}$ ,  $P_{11}$ ,  $PS_{10}$ ,  $PS_{01}$ ,  $P_{11}^*$ ,  $P_{01}^*$ ). Note that  $P_{11}$  and  $P_{11}^*$  share the parameters  $PS_{10}$  and  $PS_{01}$ , which are invariant across populations.

on  $P_{11}^*$  (which in general will not be identified from the data), or on its bounds (which are identified)—we believe these two approaches are complementary, and we encourage investigators to explore both options (see also Richardson et al., 2011; Gustafson, 2015; Silva and Evans, 2016).

**Inference on  $P_{11}^*$ .** As discussed in the previous section, we have that  $P_{11}$  is a deterministic function of  $PS_{10}$ ,  $PS_{01}$  and  $P_{01}$ , that is,  $P_{11} = (1 - PS_{10})P_{01} + PS_{01}(1 - P_{01})$ . Therefore, we need only to specify priors for the parameters  $P_{01}$ ,  $P_{01}^*$ ,  $PS_{10}$  and  $PS_{01}$ . For example, an “uninformative” (or “flat”) prior consists of a uniform distribution over 0 and 1 for all parameters. Another option is to choose a prior that incorporates the assumption of monotonicity, by setting a point mass on  $PS_{10} = 0$ . Users have the flexibility of picking anything in between, such as setting a prior that puts most, but not all, of the mass on  $PS_{10} = 0$ , for instance. The target of inference is the *posterior distribution* of  $P_{11}^*$ , which is, again, a transformation of the parameters  $P_{01}^*$ ,  $PS_{10}$  and  $PS_{01}$ ,

$$P_{11}^* = (1 - PS_{10})P_{01}^* + PS_{01}(1 - P_{01}^*)$$

As we shall see, with a “flat” prior, as the sample size increases the posterior distribution converges to the identified bounds; whereas with a prior that assumes monotonicity the posterior converges to the identified point estimate. Other quantities of interest may be the posterior distribution of certain *effect*



*measures*, such as the risk difference  $RD^* = P_{11}^* - P_{01}^*$  or the risk ratio  $RR^* = P_{11}^*/P_{01}^*$ . Figure 4 shows the probabilistic graphical model of this setup, with observed variables in gray, and latent parameters in white. The known fixed parameters  $N_0$ ,  $N_1$  and  $N_0^*$  are omitted for clarity.

**Inference on bounds.** When making inferences on  $P_{11}^*$  (which is not identified), the shape of its posterior will be dependent on (but not completely determined by) the shape of the prior of the unidentified quantities  $PS_{01}$  and  $PS_{10}$ , regardless of sample size. For this reason, users may also find useful to perform inference directly on the bounds  $P_{11}^{*L}$  and  $P_{11}^{*U}$  (which are identified). While the previous framework can still be used for such inferences, we note that, if interest lies on the bounds alone, there is a simpler alternative—as the bounds are functionals of the observed data, inference about  $P_{11}^{*L}$  and  $P_{11}^{*U}$  only requires priors on the identified parameters  $P_{01}$ ,  $P_{11}$  and  $P_{01}^*$  (Richardson et al., 2011; Silva and Evans, 2016).

**Sampling.** Given the observed data  $\mathcal{D}$  and a prior distribution on the parameters, one can obtain the posterior distribution of the target quantities using Gibbs sampling. Here we use the Gibbs sampler JAGS (Plummer et al., 2003). Extending the model to two (or more) source populations follows the same logic, thus we defer its discussion to Appendix A.4. Next, we demonstrate the method using: (i) simulated data from the Russian Roulette example; and, (ii) real data from trials that investigate the effects of vitamin A supplementation on childhood mortality. Code for replicating all results is also provided in Appendix A.4.

## Simulated data example

To illustrate the method, we start by applying our tools to simulated data drawn from a process with the same proportions as the Russian Roulette example, with various sample sizes. We show the posterior distribution of  $P^*(Y_1 = 1)$  using both a “flat” prior for all parameters, and a prior assuming monotonicity. The results are shown in Figures 5 and 6.

Let us start by examining Figure 5. Here we set “flat” priors for *all* parameters. Note that, as per Theorem 1, the posterior distribution remains spread in the asymptotic bounds of 16.8% and 20.8% regardless of sample size. Moving to Figure 6, we now set a point mass prior on  $PS_{10} = 0$ ,

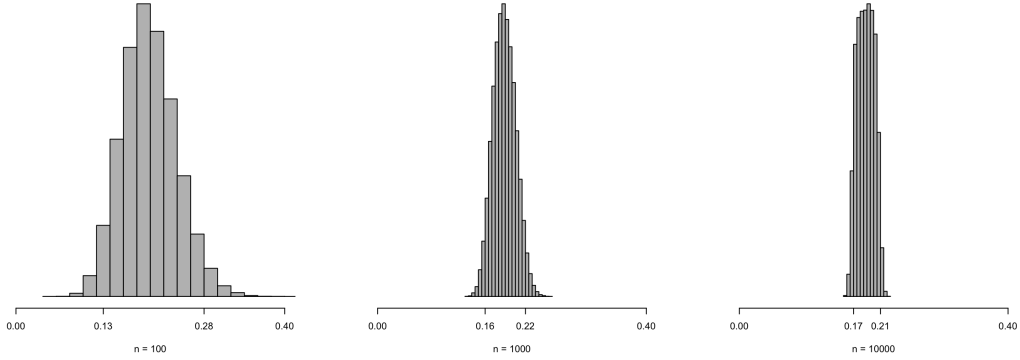


Figure 5: Histograms of the posterior samples of  $P^*(Y_1 = 1)$  for a simulation of the Russian Roulette data, considering different sample sizes 100, 1,000 and 10,000. Here all parameters have a “flat” prior. Note that, as the sample size increases, the posterior distribution does not concentrate on a point; rather, the posterior remains spread on the identified bound of 16.8% to 20.8%, as per Theorem 1.

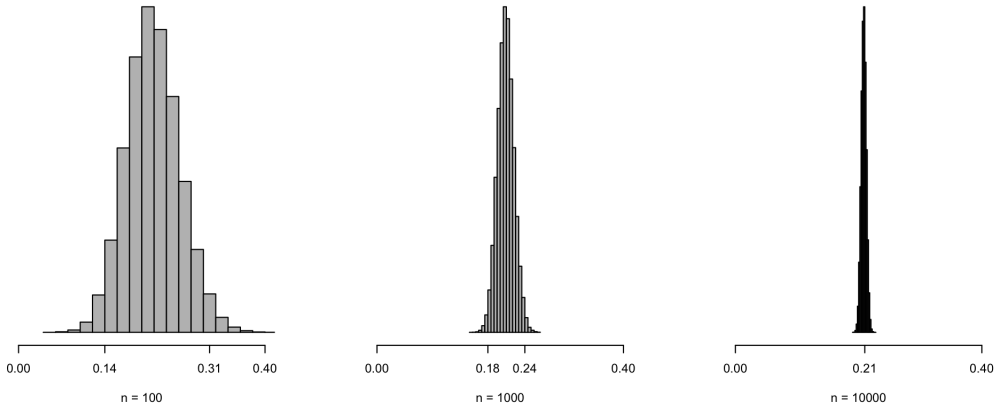


Figure 6: Histograms of the posterior samples of  $P^*(Y_1 = 1)$  for a simulation of the Russian Roulette data, considering different sample sizes 100, 1,000 and 10,000. Here we put a point mass prior on  $PS_{10}$ , corresponding to the assumption of monotonicity. The remaining parameters have a “flat” prior. Note that, as the sample size increases, the posterior distribution concentrates on 20.8%, since the parameter is identifiable in this setting.

representing the assumption of monotonicity. The remaining parameters continue to have a “flat” prior. As expected, the posterior distribution now concentrates around 20.8% as the number of cases increases.

## Real data example

We now illustrate our method with a real data example. We investigate three experiments designed to determine the effects of vitamin A supplementation on childhood mortality. The first trial was carried out in the Aceh province at the northern tip of Sumatra, Indonesia (Sommer et al., 1986); the second trial was conducted in the West Java province, in Java, also in Indonesia (Muhilal et al., 1988). Finally, the third trial took place in the district of Sarlahi, Nepal (West Jr et al., 1991). The results from the studies are shown in Table 1. Our exercise in this section consists of using the results of earlier trials, along with the baseline risk of the target population, to predict mortality under treatment in the target population.

It is suspected that vitamin A reduces childhood mortality by reducing the incidence, severity or duration of life-threatening diseases such as measles and diarrhoea (West Jr et al., 1991). As a *first approximation* to this process, we can borrow the same disjunctive model of the previous section. The variables now mean: (i)  $Y = 1$  *survival*, and  $Y = 0$  death during the trial; (ii)  $H = 1$  *absence*, and  $H = 0$  presence of severe measles; (iii)  $X = 1$  participation in the treatment group (vitamin A supplementation), and  $X = 0$  participation in the control group; finally, (iv)  $B$  summarizes biological factors that determine the response to treatment ( $B = 1$  successful response,  $B = 0$  otherwise). Here the monotonicity assumption states that vitamin A supplementation *does not* cause deaths. After presenting the results of our method, we discuss cases under which these assumptions may be violated,

Study	Treatment		Control	
	Survived	Total	Survived	Total
Aceh (Sommer et al., 1986)	12,890	12,991	12,079	12,209
West Java (Muhilal et al., 1988)	5,589	5,775	5,195	5,445
Sarlahi (West Jr et al., 1991)	14,335	14,487	13,933	14,143

Table 1: Observed data for the vitamin A studies.

thus preventing one from inferring  $Y_1 \perp\!\!\!\perp S \mid Y_0$ .

Our first task is to use the results of the Aceh trial ( $\Pi^A$ ) to predict the effects of the West Java trial ( $\Pi^{WJ}$ ). The estimates of the Aceh trial are  $\hat{P}^A(Y_1 = 1) = 0.992$  and  $\hat{P}^A(Y_0 = 1) = 0.989$ ; whereas the baseline risk in the Java trial is  $\hat{P}^{WJ}(Y_0 = 1) = 0.954$ . As expected, note the large discrepancy of baseline risk in both trials, indicating the existence of structural differences in how mortality is determined, and thus forbidding a direct transport of  $P^{WJ}(Y_1 = 1)$ . Figure 7 shows the posterior distribution of  $P^{WJ}(Y_1 = 1)$  using both a “flat” prior for all parameters (left), and a prior assuming monotonicity for the effect of vitamin A supplementation (right). In the first case, we obtain a 95% *credible interval* of 0.962 to 0.992 for  $P^{WJ}(Y_1 = 1)$ , in agreement with the asymptotic bounds of Theorem 1—this shows that, even without assuming monotonicity, the bounds are narrow enough to be consistent with a positive effect of vitamin A supplementation in West Java.<sup>12</sup> When assuming a monotonic effect of vitamin A, we obtain the posterior mean of 0.967 (95% CI 0.956–0.975). In both plots, a red dashed line indicates the actual value observed in the West Java trial,  $\hat{P}^{WJ}(Y_1 = 1) = 0.968$ , which is consistent with the predictions of our method.

Our second task is to use the results of *both* the Aceh ( $\Pi^A$ ) and West Java ( $\Pi^{WJ}$ ) trials to predict the effects of the Sarlahi trial ( $\Pi^S$ ). As per Theorems 2 and 3, in this setting we can identify the probabilities of sufficiency shared across regions,  $PS_{10}$  and  $PS_{01}$ , as well as the effect in Sarlahi,  $P^S(Y_1 = 1)$ , *without* assuming monotonicity. The posterior distributions of these three quantities are displayed in Figure 8. The posterior mean for  $PS_{01}$  is 0.346 (95% CI 0.214–0.478), while the posterior mean for  $PS_{10}$  is 0.001 (95% CI 0.000–0.004). This suggests that, in the context of these trials, vitamin A supplementation is sufficient to prevent 21% to 48% of the deaths that would have otherwise occurred without supplementation, while it has no or little side-effects that are sufficient to cause the death of otherwise healthy subjects. Finally, we obtain the posterior mean of 0.989 (95% CI 0.987–0.991) for  $P^S(Y_1 = 1)$ , consistent with the actual value observed in the Sarlahi trial,  $\hat{P}^S(Y_1 = 1) = 0.989$ .

Before moving to the conclusions, let us use this example to make some

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<sup>12</sup>The 95% credible intervals for the risk difference and risk ratio are 0.008–0.04 and 1.009–1.042, respectively. Alternatively, if one prefers inferences on the bounds, we have 95% credible intervals of: 0.955–0.975 for the lower bound, 0.991–0.994 for the upper bound, and 0.002–0.020 for the lower bound of the risk difference (i.e.,  $P_{11}^{*L} - P_{01}^*$ ).

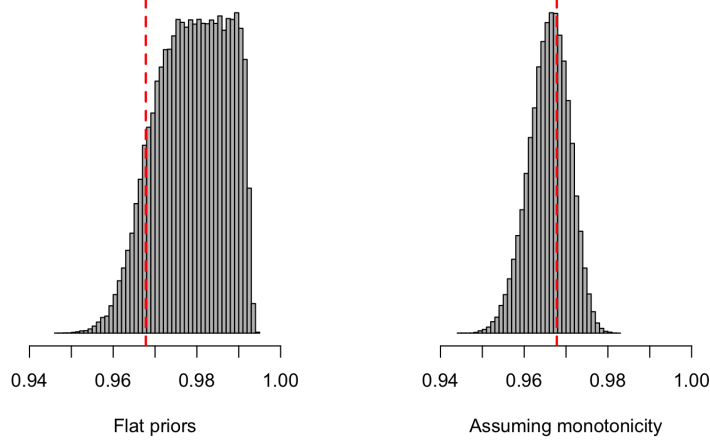


Figure 7: Posterior of  $P^{WJ}(Y_1 = 1)$  for the West Java trial, using data from the Aceh trial. Left: posterior of  $P^{WJ}(Y_1 = 1)$  using “flat” priors. Right: posterior of  $P^{WJ}(Y_1 = 1)$  assuming monotonicity. Red dashed lines show the observed value in the West Java trial,  $\hat{P}^{WJ}(Y_1 = 1)$ .

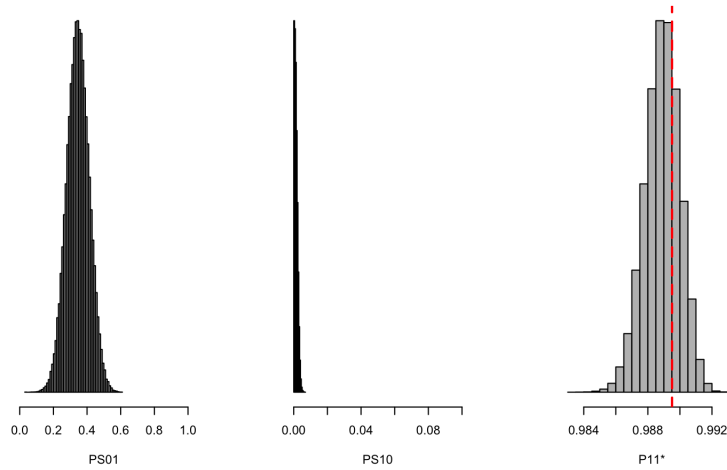


Figure 8: From left to right, posterior of  $PS_{01}$ ,  $PS_{10}$  and  $P^S(Y_1 = 1)$  using data from *both* the Aceh and West Java trials (Sommer et al., 1986; Muhilal et al., 1988), and using “flat” priors for all parameters. Dashed red line indicates the observed value in the Sarlahi trial,  $\hat{P}^S(Y_1 = 1)$ .

brief remarks about causal modeling in practice. Note that the working model in this section assumes the only factor causing deaths during the period of the trial can be summarized by  $H$ , consisting of diseases which, at least in principle, can be affected by the treatment (e.g, severe measles or diarrhoea). What happens, however, if we augment the model to allow for other causes of deaths unaffected by vitamin  $A$  supplementation? It can be shown that this new variable is a common cause of both potential responses, thus creating a colliding path and forbidding the conclusion that  $Y_1 \perp\!\!\!\perp S \mid Y_0$ .<sup>13</sup> This suggests caution when transporting these results to populations where mortality due to diarrhoea or measles is not predominant.

More generally, while one may summarize the main “identification assumption” for the results in this paper in terms of the counterfactual independence  $Y_1 \perp\!\!\!\perp S \mid Y_0$ , note we did not commence the analysis by imposing this or any “identification assumption.” Instead, we made an effort to explicate our understanding of the problem directly in a structural model, and the necessary counterfactual independence emerged naturally as a *logical consequence of the structure*. This is an important part of the process. If some of those modeling assumptions happen to be challenged, as they often are in practical settings (e.g, unobserved confounding between  $H$  and  $B$ ), we should refrain from positing that  $Y_1 \perp\!\!\!\perp S \mid Y_0$  and the model both warns us of possible threats, as well as helps us in finding alternative solutions.<sup>14</sup>

## 5 Conclusions

This paper showed how two apparently separate areas of causal inference research—the generalization of causal effects across populations (Pearl and Bareinboim, 2014; Bareinboim and Pearl, 2016; Huitfeldt et al., 2018) and the identification of “causes of effects” (Pearl, 1999; Tian and Pearl, 2000; Pearl, 2015, 2019)—can be merged for mutual benefit, unveiling important results in both areas.

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<sup>13</sup>Call these new causes  $C$ . The new structural equation for  $Y$  now reads  $Y = (H \vee (X \wedge B)) \wedge \neg C$ . This leads to  $Y_0 = H \wedge \neg C$  and  $Y_1 = Y_0 \vee (B \wedge \neg C)$ . Note this creates the colliding path  $S \rightarrow H \rightarrow Y_0 \leftarrow C \rightarrow Y_1$ , thus forbidding the conclusion that  $Y_1 \perp\!\!\!\perp S \mid Y_0$ , even when there is no selection node pointing directly to  $C$ . For another illustration of when collider bias may arise, see Appendix A.3.

<sup>14</sup>For example, a sensitivity analysis might still be possible, and one could investigate how big a departure from the original model assumptions would be necessary to invalidate the main conclusions. See, e.g., Cinelli et al. (2019); Cinelli and Hazlett (2020).

The first lesson that emerges from this combined analysis is that certain functional constraints may entail the invariance of probabilities of causation across domains, which can then be used as instruments to license generalization. This may occur when the outcome is a product of several independent processes, only some of which are carriers of disparities, and when the outcome produced under the “no-treatment” condition is sufficient to block these sources of disparity. These functional constraints may enable the identification, or at least the bounding of the target effect in settings where non-parametric generalization is otherwise impossible.

A second lesson that surfaces from our investigation is that, whenever experimental data from multiple sites are available, these may lead to the point identification of probabilities of causation. These counterfactual probabilities can be the targets of investigations in public health, legal settings, and the production of explanations (Mueller and Pearl, 2020; Pearl, 2015, 2019). For example, drugs with a positive average treatment effect may still kill individuals who would have otherwise survived—being able to quantify the percentage of individuals that are saved or harmed by the treatment has important implications in many public health applications.

The development of tools for automating the types of analyses presented here, paralleling those available for non-parametric models, is a challenging topic for future work. As we have seen, determining the invariance of probabilities of causation requires additional constraints beyond the standard non-parametric model; some recent developments, such as algorithms for handling context-specific independencies for causal identification (Tikka et al., 2019), may provide the initial steps towards this undertaking.

## **Conflict of interest**

The authors declare that they have no conflict of interest.

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# A Appendix

## A.1 An example with continuous treatment

Here we provide a simple example in which, although the treatment variable is continuous, the relevant dependencies among potential outcomes are still amenable to graphical representation. Suppose we have the same selection diagram as in Figure 2b, but now let  $X$ ,  $B$ , and  $H$  all be continuous variables. Next, consider the following functional specification for the structural equation of  $Y$ ,

$$Y = I(H > 0) \vee I(X \times B > 0) \tag{10}$$

Where  $I(\cdot)$  denotes the indicator function. Now note from Equation 10 we can derive the potential outcomes  $Y_0 = I(H > 0)$  for  $x = 0$ , and,  $Y_x = I(H > 0) \vee I(xB > 0) = Y_0 \vee I(xB > 0)$ , for  $x \neq 0$ . We can thus draw the same modified selection diagram as in Figure 3, but now replacing  $Y_1$  with  $Y_x$ , leading to the conclusion that  $Y_x \perp\!\!\!\perp S \mid Y_0$ , for all  $x \neq 0$ .

## A.2 Proofs

### A.2.1 Bounds with a single source population

Here we show how to obtain the bounds of Theorem 1. To simplify notation, let  $P_{ij} := P(Y_i = j)$ ,  $P_{ij}^* := P^*(Y_i = j)$ ,  $\text{PS}_{10} := P^*(Y_1 = 0 \mid Y_0 = 1) = P(Y_1 = 0 \mid Y_0 = 1)$  and  $\text{PS}_{01} = P^*(Y_1 = 1 \mid Y_0 = 0) = P(Y_1 = 1 \mid Y_0 = 0)$ . The target function to be optimized is  $P_{11}^*$ , which can be written as,

$$P_{11}^* = (1 - \text{PS}_{10})P_{01}^* + \text{PS}_{01}(1 - P_{01}^*) \tag{11}$$

Our goal is to pick  $\text{PS}_{10}$  and  $\text{PS}_{01}$  such that it maximizes (or minimizes) Eq. 11 subject to the following constraints: (i)  $\text{PS}_{10}$  and  $\text{PS}_{01}$  need to be between zero and one (since  $\text{PS}_{10}$  and  $\text{PS}_{01}$  need to be valid probabilities); and, (ii)  $\text{PS}_{10}$  and  $\text{PS}_{01}$  must conform to the observed results of the trial in the source domain, that is,  $P_{11} = (1 - \text{PS}_{10})P_{01} + \text{PS}_{01}(1 - P_{01})$ . Thus, our

optimization problem is,

$$\begin{aligned} \max_{\text{PS}_{10}, \text{PS}_{01}} \quad & P_{11}^* = (1 - \text{PS}_{10})P_{01}^* + \text{PS}_{01}(1 - P_{01}^*) \\ \text{s.t.} \quad & P_{11} = (1 - \text{PS}_{10})P_{01} + \text{PS}_{01}(1 - P_{01}) \\ \text{and} \quad & 0 \leq \text{PS}_{10} \leq 1, \quad 0 \leq \text{PS}_{01} \leq 1 \end{aligned}$$

To simplify the problem, we can use the equality constraint  $P_{11} = (1 - \text{PS}_{10})P_{01} + \text{PS}_{01}(1 - P_{01})$  to eliminate one of the variables. For instance, writing  $\text{PS}_{10}$  in terms of  $\text{PS}_{01}$  gives us,

$$1 - \text{PS}_{10} = \frac{P_{11} - \text{PS}_{01}(1 - P_{01})}{P_{01}} \quad (12)$$

Which results in a new target function,

$$P_{11}^* = (1 - \text{PS}_{10})P_{01}^* + \text{PS}_{01}(1 - P_{01}^*) \quad (13)$$

$$= \left( \frac{P_{11} - \text{PS}_{01}(1 - P_{01})}{P_{01}} \right) P_{01}^* + \text{PS}_{01}(1 - P_{01}^*) \quad (14)$$

$$= \left( \frac{P_{11}}{P_{01}} \right) P_{01}^* + \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) \text{PS}_{01} \quad (15)$$

$$= RR \times P_{01}^* + \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) \text{PS}_{01} \quad (16)$$

Where  $RR = \frac{P_{11}}{P_{01}}$  is the causal *risk-ratio* in the trial of the source domain  $\Pi$ . Since  $0 \leq (1 - \text{PS}_{10}) \leq 1$ , the substitution also results in additional constraints on  $\text{PS}_{01}$ ,

$$\frac{P_{11} - P_{01}}{1 - P_{01}} \leq \text{PS}_{01} \leq \frac{P_{11}}{1 - P_{01}} \quad (17)$$

Thus, define the lower and upper bounds on  $\text{PS}_{01}$  as

$$\text{PS}_{01}^L = \max \left\{ 0, \frac{P_{11} - P_{01}}{1 - P_{01}} \right\}, \quad \text{PS}_{01}^U = \min \left\{ \frac{P_{11}}{1 - P_{01}}, 1 \right\}$$

Our new maximization problem can be written as,

$$\max_{\text{PS}_{01}} RR \times P_{01}^* + \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) \text{PS}_{01} \quad \text{s.t.} \quad \text{PS}_{01}^L \leq \text{PS}_{01} \leq \text{PS}_{01}^U \quad (18)$$

Since the target function is linear, the maximum occurs at the extreme points of  $\text{PS}_{01}$ . The same reasoning holds for the minimization problem. Thus, we have that,

$$P_{11}^{*L} \leq P_{11}^* \leq P_{11}^{*U}$$

Where,

$$P_{11}^{*L} = RR \times P_{01}^* + \min \left\{ \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) \text{PS}_{01}^L, \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) \text{PS}_{01}^U \right\}$$

and

$$P_{11}^{*U} = RR \times P_{01}^* + \max \left\{ \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) \text{PS}_{01}^L, \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) \text{PS}_{01}^U \right\}$$

### A.2.2 Informativeness of the bounds

We now derive the width of the bounds for  $P_{11}^*$  for the case when the bounds for  $\text{PS}_{01}$  do not reach 0 nor 1 (this will happen when both  $P_{11} > P_{01}$  and  $P_{11} < 1 - P_{01}$ ). Define the width  $W$  of the bounds as the difference between the upper and lower bound of  $P_{11}^*$ , that is,

$$W = P_{11}^{*U} - P_{11}^{*L}$$

Expanding the terms we obtain,

$$W = P_{11}^{*U} - P_{11}^{*L} \quad (19)$$

$$= \left| \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) \text{PS}_{01}^U - \left( \frac{P_{01} - P_{01}^*}{P_{01}} \right) \text{PS}_{01}^L \right| \quad (20)$$

$$= \frac{|P_{01} - P_{01}^*|}{P_{01}} \times (\text{PS}_{01}^U - \text{PS}_{01}^L) \quad (21)$$

$$= \frac{|P_{01} - P_{01}^*|}{P_{01}} \times \frac{P_{01}}{1 - P_{01}} \quad (22)$$

$$= \frac{|P_{01} - P_{01}^*|}{1 - P_{01}} \quad (23)$$

Thus, when the bounds for  $\text{PS}_{01}$  are “interior,” the informativeness of the bounds depend only on  $P_{01}$  and  $P_{01}^*$ . Moreover, even if the bounds for  $\text{PS}_{01}$  are “wide,” the bounds for  $P_{11}^*$  may be “narrow,” provided the baseline risks of the source and target population are close enough.

### A.2.3 Identification with multiple source domains

We now show how to obtain the identification results of Theorem 2 and 3. Consider two source populations  $\Pi^a$  and  $\Pi^b$ . Again, to simplify notation, let  $P_{ij}^a := P^a(Y_i = j)$ ,  $P_{ij}^b := P^b(Y_i = j)$ ,  $\text{PS}_{10} := P^a(Y_1 = 0|Y_0 = 1) = P^b(Y_1 = 0|Y_0 = 1) = P^*(Y_1 = 0|Y_0 = 1)$  and  $\text{PS}_{01} := P^a(Y_1 = 1|Y_0 = 0) = P^b(Y_1 = 1|Y_0 = 0) = P^*(Y_1 = 1|Y_0 = 0)$ .

First note that  $\text{PS}_{10}$  and  $\text{PS}_{01}$  are identified from the experimental data in  $\Pi^a$  and  $\Pi^b$ . Using the law of total probability for  $P_{11}^a$  and  $P_{11}^b$  write,

$$P_{11}^a = (1 - \text{PS}_{10}) \times P_{01}^a + \text{PS}_{01} \times P_{00}^a \quad (24)$$

$$P_{11}^b = (1 - \text{PS}_{10}) \times P_{01}^b + \text{PS}_{01} \times P_{00}^b \quad (25)$$

We thus have a system of two equations and two unknowns,

$$\begin{bmatrix} P_{01}^a & P_{00}^a \\ P_{01}^b & P_{00}^b \end{bmatrix} \begin{bmatrix} (1 - \text{PS}_{10}) \\ \text{PS}_{01} \end{bmatrix} = \begin{bmatrix} P_{11}^a \\ P_{11}^b \end{bmatrix} \quad (26)$$

Yielding the solution,

$$\begin{bmatrix} (1 - \text{PS}_{10}) \\ \text{PS}_{01} \end{bmatrix} = \frac{1}{P_{01}^a P_{00}^b - P_{01}^b P_{00}^a} \times \begin{bmatrix} P_{00}^b & -P_{00}^a \\ -P_{01}^b & P_{01}^a \end{bmatrix} \begin{bmatrix} P_{11}^a \\ P_{11}^b \end{bmatrix} \quad (27)$$

Which amounts to:

$$\text{PS}_{10} = 1 - \frac{P_{11}^a P_{00}^b - P_{11}^b P_{00}^a}{P_{01}^a P_{00}^b - P_{01}^b P_{00}^a} \quad (28)$$

$$\text{PS}_{01} = \frac{P_{11}^b P_{01}^a - P_{11}^a P_{01}^b}{P_{01}^a P_{00}^b - P_{01}^b P_{00}^a} \quad (29)$$

All values of the RHS can be computed from the experimental data of  $\Pi^a$  and  $\Pi^b$ . Note that, since  $\text{PS}_{10}$  and  $\text{PS}_{01}$  must be between 0 and 1, not all solutions are valid. Therefore, two domains already entail some testable implications—if either  $\text{PS}_{10}$  and  $\text{PS}_{01}$  are not valid probabilities, this means that the assumption that the probabilities of sufficiency are invariant across domains is false. If we add a third or more source domains, it is easy to see that we will have three or more equations but still only two unknowns, and the system is thus over-identified.

Once in possession of  $\text{PS}_{10}$  and  $\text{PS}_{01}$ , we can transport of the causal effect to the target population  $\Pi^*$  by appealing again to the law of total probability,

$$P_{11}^* = (1 - \text{PS}_{10}) \times P_{01}^* + \text{PS}_{01} \times P_{00}^* \quad (30)$$

$$= \frac{P_{11}^a P_{00}^b - P_{11}^b P_{00}^a}{P_{01}^a P_{00}^b - P_{01}^b P_{00}^a} \times P_{01}^* + \frac{P_{11}^b P_{01}^a - P_{11}^a P_{01}^b}{P_{01}^a P_{00}^b - P_{01}^b P_{00}^a} \times P_{00}^* \quad (31)$$

Finally, we note that all probabilities of causation, as discussed in Tian and Pearl (2000), are also identifiable in this setting. First, consider the *probability of necessity and sufficiency*,  $\text{PNS} = P(Y_1 = 1, Y_0 = 0)$  for  $\Pi^a$ . Using the chain rule,  $\text{PNS}$  can be written as,

$$P^a(Y_1 = 1, Y_0 = 0) = P^a(Y_1 = 1 | Y_0 = 0) P^a(Y_0 = 0) \quad (32)$$

$$= \text{PS}_{01} \times P^a(Y_0 = 0) \quad (33)$$

Note  $\text{PS}_{01}$  was already identified, and  $P^a(Y_0 = 0)$  is given by the trial data in  $\Pi^a$ , thus rendering  $\text{PNS}^a$  identifiable. Similar reasoning holds for  $\Pi^b$ .

For the *probability of necessity*, define  $\text{PN}_{01} := P(Y_0 = 0 | Y_1 = 1)$ . Due to the randomization of  $X$ ,  $\text{PN}_{01}$  coincides with Tian and Pearl's probability of

necessity *during the trial* (not the observational PN), by the same argument we provide for PS in the main text. The final step is to note that,

$$P^a(Y_0 = 0 \mid Y_1 = 1) = \frac{P^a(Y_0 = 0, Y_1 = 1)}{P^a(Y_1 = 1)} = \frac{\text{PNS}^a}{P^a(Y_1 = 1)}$$

The numerator is simply the PNS, which we have already identified, and the denominator is given by the trial data in  $\Pi^a$ . Again, analogous argument can be given for  $\Pi^b$ .

### A.3 Modeling functional constraints

To illustrate the usefulness of explicitly modeling functional constraints in a structural framework, we apply the same modeling strategy of the paper in an example described in Huitfeldt et al. (2018, p. 11):

Consider a team of investigators who are interested in the effect of antibiotic treatment on mortality in patients with a specific bacterial infection (...) the investigators believe that the response to this antibiotic is completely determined by an unmeasured bacterial gene, such that only those who are infected with a bacterial strain with this gene respond to treatment. The prevalence of this bacterial gene is equal between populations, because the populations share the same bacterial ecosystem (...) if the investigators further believe that the gene for susceptibility reduces the mortality in the presence of antibiotics, but has no effect in the absence of antibiotics, they will conclude that  $G$  may be equal between populations.

Here the conclusion that  $G$  may be equal between populations is equivalent to claiming  $Y_1 \perp\!\!\!\perp S \mid Y_0$ . But is the description above sufficient for substantiating this claim? Figure 9 shows two models compatible with the description, yet leading to two opposite conclusions.

Let the variable  $A$  represent the binary treatment (antibiotic),  $Y$  represent the binary outcome (mortality),  $BG$  stand for the presence or absence of the “bacterial gene” and finally let  $U$  be a binary variable that summarizes all other factors that may cause death ( $Y = 1$ ). The description of the problem suggests the functional specification,

$$Y = U \wedge (\neg A \vee \neg BG) \tag{34}$$



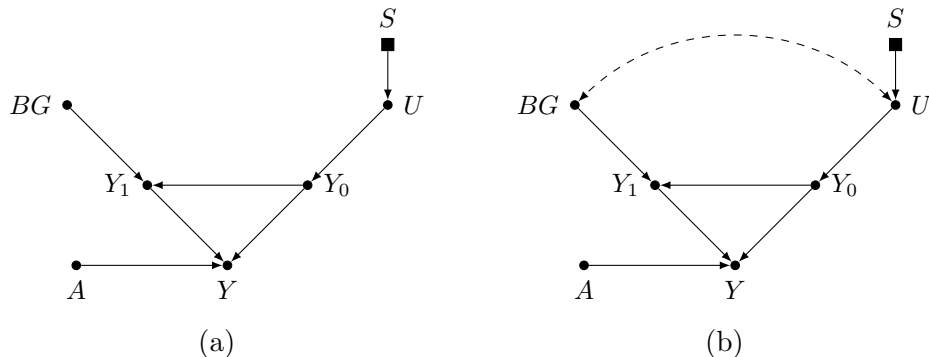


Figure 9: Two selection diagrams compatible with the verbal description of Huitfeldt et al. (2018, page 11). Yet, model (a) implies  $Y_1 \perp\!\!\!\perp S \mid Y_0$ , and model (b) implies the opposite; conditioning on  $Y_0$  opens the colliding path  $S \rightarrow U \leftrightarrow BG \rightarrow Y_1$ .

showing the antibiotics and the bacterial gene both helping to *reduce* mortality ( $\neg$  denotes the logical “not”). Equation 34 entails the potential outcomes  $Y_0 = U$  and  $Y_1 = U \wedge (\neg BG) = Y_0 \wedge (\neg BG)$ , which are explicitly shown in both diagrams as dictated by the functional specification. Moreover, in both models the prevalence of the bacterial gene  $BG$  is equal between populations (i.e.,  $BG \perp\!\!\!\perp S$ ). In the model of Figure 9a, as in our previous analysis, we indeed conclude that  $Y_1 \perp\!\!\!\perp S \mid Y_0$ , and that  $P^*(Y_1)$  is transportable. However, in the model of Figure 9b, there is an unmeasured confounder between  $BG$  and  $U$ .<sup>15</sup> Conditioning on  $Y_0$  (a child of a collider) opens the colliding path  $S \rightarrow U \leftrightarrow BG \rightarrow Y_1$ , thus not licensing the independence  $Y_1 \perp\!\!\!\perp S \mid Y_0$ .

## A.4 Bayesian estimation

### A.4.1 Multiple source domains

In this section we show how to extend the probabilistic graphical model of Section 4 to two or more sources. Let us start with two source populations  $\Pi^a$  and  $\Pi^b$ , and one target domain  $\Pi^*$ . The observed data is now

<sup>15</sup>This could arise, for instance, as a result of population stratification.

$\mathcal{D} = \{n_0^a, n_1^a, n_0^*, n_0^b, n_1^b\}$ , all with binomial distributions:

$$n_0^a \sim \text{Binomial}(N_0^a, P_{01}^a) \quad (35)$$

$$n_1^a \sim \text{Binomial}(N_1^a, P_{11}^a) \quad (36)$$

$$n_0^* \sim \text{Binomial}(N_0^*, P_{01}^*) \quad (37)$$

$$n_0^b \sim \text{Binomial}(N_0^b, P_{01}^b) \quad (38)$$

$$n_1^b \sim \text{Binomial}(N_1^b, P_{11}^b) \quad (39)$$

We also have the following deterministic relationships for  $P_{11}^a$ ,  $P_{11}^b$  and  $P_{11}^*$ :

$$P_{11}^a = (1 - \text{PS}_{10})P_{01}^a + \text{PS}_{01}(1 - P_{01}^a) \quad (40)$$

$$P_{11}^b = (1 - \text{PS}_{10})P_{01}^b + \text{PS}_{01}(1 - P_{01}^b) \quad (41)$$

$$P_{11}^* = (1 - \text{PS}_{10})P_{01}^* + \text{PS}_{01}(1 - P_{01}^*) \quad (42)$$

The probabilistic graphical model for this case is shown in Figure 10.

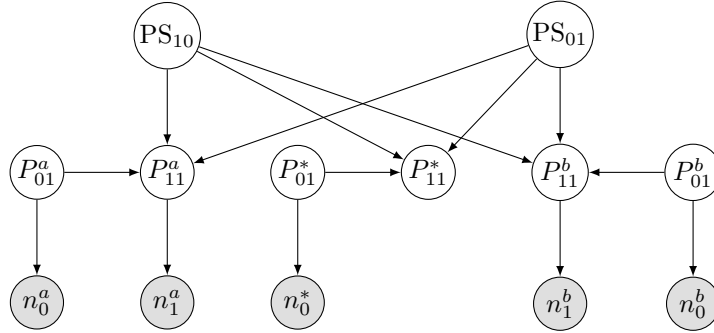


Figure 10: Probabilistic graphical model with two source populations  $\Pi^a$ ,  $\Pi^b$  and one target population  $\Pi^*$ . Gray nodes ( $n_0^a$ ,  $n_1^a$ ,  $n_0^*$ ,  $n_0^b$ ,  $n_1^b$ ) denote observed variables. White nodes denote latent parameters ( $P_{01}^a$ ,  $P_{11}^a$ ,  $\text{PS}_{10}$ ,  $\text{PS}_{01}$ ,  $P_{01}^*$ ,  $P_{11}^*$ ,  $P_{01}^b$ ,  $P_{11}^b$ ). Note that  $P_{11}^a$ ,  $P_{11}^*$  and  $P_{11}^b$  share the parameters  $\text{PS}_{10}$  and  $\text{PS}_{01}$ , which are invariant across populations.

Thus, one needs to place priors on the parent nodes only, and then perform inference as before. The extension to more than two populations follows the same logic. It is worth noting that, as we have seen in Section 3, with two or more source populations the model entails testable implications. Therefore, we advise researchers to check whether the data is compatible with the model (Gelman et al., 2013).

Finally, similarly to the discussion in Section 4, a simpler modeling alternative here is to place priors only on the parameters of the observed data directly, and make inferences using the posterior of the functionals of the observed data that identify the target quantities.

#### A.4.2 Replication code

Here we provide R code to replicate the estimation examples using JAGS (Plummer et al., 2003) and the package `rjags` (Plummer, 2016).

```
### Replication code for
### "Generalizing Experimental results
### by Leveraging Knowledge of Mechanisms"
### -- Carlos Cinelli and Judea Pearl

# Set up -----

## Cleans workspace
rm(list = ls())

## Loads necessary R packages
library(rjags)

## JAGS models

model_one_source <-
  "model{

    # Likelihood
    n0 ~ dbinom(p01, N0)
    n1 ~ dbinom(p11, N1)
    n0s ~ dbinom(p01s, N0s)

    # Priors
```

```

PS10 ~ dbeta(1,1)
PS01 ~ dbeta(1,1)
p01 ~ dbeta(1, 1)
p01s ~ dbeta(1, 1)

# Computed quantities
p11 <- (1-PS10)*p01 + PS01*(1-p01)
p11s <- (1-PS10)*p01s + PS01*(1-p01s)
rd <- p11s - p01s
rr <- p11s/p01s

# bounds
PS01_l <- max(0, (p11-p01)/(1-p01))
PS01_u <- min(p11/(1-p01), 1)

p11_1 <- (1-p01s/p01)*PS01_l + (p01s/p01)*p11
p11_2 <- (1-p01s/p01)*PS01_u + (p01s/p01)*p11
p11_l <- min(p11_1, p11_2)
p11_u <- max(p11_1, p11_2)
rd_l <- p11_l - p01s
rr_l <- p11_l/p01s

}"

model_one_source_monotonic <-
  "model{

# Likelihood
n0 ~ dbinom(p01, N0)
n1 ~ dbinom(p11, N1)
n0s ~ dbinom(p01s, N0s)

# Priors
PS10 <- 0
PS01 ~ dbeta(1,1)
p01 ~ dbeta(1, 1)

```

```

p01s ~ dbeta(1, 1)

# Computed quantities
p11 <- (1-PS10)*p01 + PS01*(1-p01)
p11s <- (1-PS10)*p01s + PS01*(1-p01s)
rd <- p11s - p01s
rr <- p11s/p01s
}"

model_two_sources <- "model{

# Likelihood
n0a ~ dbinom(p01a, N0a)
n0b ~ dbinom(p01b, N0b)
n0c ~ dbinom(p01c, N0c)
n1a ~ dbinom(p11a, N1a)
n1b ~ dbinom(p11b, N1b)

# Priors
p01a ~ dbeta(1, 1)
p01b ~ dbeta(1, 1)
p01c ~ dbeta(1, 1)
PS10 ~ dbeta(1, 1)
PS01 ~ dbeta(1, 1)

# Computed quantities
p11a <- (1-PS10)*p01a + PS01*(1-p01a)
p11b <- (1-PS10)*p01b + PS01*(1-p01b)
p11c <- (1-PS10)*p01c + PS01*(1-p01c)
rra <- (p11a)/(p01a)
rrb <- (p11b)/(p01b)
rrc <- (p11c)/(p01c)

}"

```

```

# Simulated data example -----

loop_n <- c(1e2, 1e3, 1e4)

### Without monotonicity
par(mfrow = c(1, 3))

for(n in loop_n){
  # creates data
  data <- list(
    NO = n,
    n0 = sum(rbinom(n, 1, prob = 0.01)),
    N1 = n,
    n1 = sum(rbinom(n, 1, prob = 0.175)),
    NOs = n,
    n0s = sum(rbinom(n, 1, prob = 0.05))
  )

  # posterior samples
  model <- jags.model(textConnection(model_one_source),
    data = data)

  samples <- coda.samples(model = model,
    variable.names = c("p01", "p01s", "p11", "p11s"),
    n.iter = 100000)

  samp.data <- as.data.frame(samples[[1]])

  hist(samp.data$p11s,
    main = "",
    xlim = c(0, .4),
    yaxt = "n",
    xaxt = "n",
    xlab = paste0("n = ", n),
    ylab = "",
    col = "gray")
}

```

```

labs <- round(quantile(data$p11s, c(0.025, 0.975)), 2)
axis(side = 1, at = c(0, labs, .4))
}

### With monotonicity
par(mfrow = c(1, 3))

for(n in loop_n){

  data <- list(
    NO = n,
    n0 = sum(rbinom(n, 1, prob = 0.01)),
    N1 = n,
    n1 = sum(rbinom(n, 1, prob = 0.175)),
    NOs = n,
    n0s = sum(rbinom(n, 1, prob = 0.05))
  )

  # posterior samples
  model <- jags.model(textConnection(model_one_source_monotonic),
    data = data)

  samples <- coda.samples(model = model,
    variable.names = c("p01", "p01s", "p11", "p11s"),
    n.iter = 100000)

  samp.data <- as.data.frame(samples[[1]])

  hist(samp.data$p11s,
    main = "",
    xlim = c(0, .4),
    yaxt = "n",
    xaxt = "n",
    xlab = paste0("n = ", n),
    ylab = "",
    col = "gray")
}

```

```

    labs <- round(quantile(data$p11s, c(0.025, 0.975)), 2)
    axis(side = 1, at = c(0, labs, .4))
}

```

```

# Vitamin A example -----

```

```

### Vitamin A data

```

```

### Aceh study

```

```

Aceh    <- data.frame(N0 = 12209,
                      n0 = 12079,
                      N1 = 12991,
                      n1 = 12890)

```

```

### West Java study

```

```

West.Java <- data.frame(N0 = 5445,
                        n0 = 5195,
                        N1 = 5775,
                        n1 = 5589)

```

```

### Sarlahi Study

```

```

Sarlahi <- data.frame(N0 = 14143,
                      n0 = 13933,
                      N1 = 14487,
                      n1 = 14335)

```

```

## Transporting: Aceh -> West Java

```

```

### Data

```

```

data <- list(N0 = Aceh$N0,
             n0 = Aceh$n0,
             N1 = Aceh$N1,
             n1 = Aceh$n1,
             N0s = West.Java$N0,

```



```

n0s = West.Java$n0)

### Posterior samples bounds
model.bounds <- jags.model(textConnection(model_one_source),
                           data = data, n.chains = 4, n.adapt = 1e3)

## burn-in
update(model.bounds, n.iter = 1e4)

## samples
samp.bounds <- coda.samples(model.bounds,
                            variable.names = c("p01","p01s", "p11",
                                                "PS01", "PS10", "p11s",
                                                "rd", "rr",
                                                "PS01_l", "PS01_u",
                                                "p11_l", "p11_u",
                                                "rd_l", "rr_l"),
                            n.iter = 100000)

summary(samp.bounds)

## extract data.frame
sim.bounds <- do.call("rbind", samp.bounds)
sim.bounds <- as.data.frame(sim.bounds)

### Posterior samples monotonic
model.monotonic <- jags.model(textConnection(model_one_source_monotonic),
                              data = data, n.chains = 4, n.adapt = 1e3)

## burn-in
update(model.monotonic, n.iter = 1e4)

## samples
samp.monotonic <- coda.samples(model.monotonic,
                               variable.names = c("p01","p01s", "p11",
                                                  "PS01", "PS10", "p11s",

```

```

                                                                    "rd", "rr"),
n.iter = 100000)
summary(samp.monotonic)

## extract data.frame
sim.monotonic <- do.call("rbind", samp.monotonic)
sim.monotonic <- as.data.frame(sim.monotonic)

## plot
par(mfrow = c(1, 2))
lims <- c(0.94,1)
mark <- West.Java$n1/West.Java$N1

hist(sim.bounds$p11s,
      breaks = 50,
      main = "",
      xlim = lims,
      yaxt = "n",
      xlab = "Flat priors",
      ylab = "",
      col = "gray")
abline(v = mark, col = "red", lty = 2, lwd = 2)

hist(sim.monotonic$p11s,
      breaks = 50,
      main = "",
      xlim = lims,
      yaxt = "n",
      xlab = "Assuming monotonicity",
      ylab = "",
      col = "gray")
abline(v = mark, col = "red", lty = 2, lwd = 2)

## Transporting: Aceh + West Java -> Sarlahi

### Data
data2 <- list(N0a = Aceh$N0,

```

```

n0a = Aceh$n0,
N1a = Aceh$N1,
n1a = Aceh$n1,
N0b = West.Java$N0,
n0b = West.Java$n0,
N1b = West.Java$N1,
n1b = West.Java$n1,
N0c = Sarlahi$N0,
n0c = Sarlahi$n0)

### Posterior samples two sources
model2 <- jags.model(textConnection(model_two_sources),
                    data = data2, n.chains = 4, n.adapt = 1e3)

## burn in
update(model2, n.iter = 1e4)

## samples
samp2 <- coda.samples(model2,
                      variable.names = c("p01a", "p01b", "p01c",
                                           "p11a", "p11b", "p11c",
                                           "PS01", "PS10",
                                           "rra", "rrb", "rrc"),
                      n.iter = 100000)

summary(samp2)

## extract data.frame
sim2 <- as.data.frame(samp2[[1]])

### Plot
par(mfrow = c(1, 3))
mark <- Sarlahi$n1/Sarlahi$N1
hist(sim2$PS01, xlim = c(0,1), breaks = 50,
     yaxt = "n", col = "gray", main = "", xlab = "PS01", ylab = "")
hist(sim2$PS10, xlim = c(0, 0.1),
     yaxt = "n", col = "gray", main = "", xlab = "PS10", ylab = "")

```

```
hist(sim2$p11c,  
      yaxt = "n", col = "gray", main = "", xlab = "P11*", ylab = "")  
abline(v = mark, col = "red", lty = 2, lwd = 2)
```